On Optimal, Minimal BRDF Sampling for Reflectance Acquisition Supplementary material

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1 RMS Errors

The following figures present RMS errors for reconstructions of all 100 MERL materials. The reconstructions are done using our 5 best points of sampling (blue), and the 5 common industry directions (red). PC projections (dashed lines) are omitted as the materials are part of the PC training.



Figure 1: RMS error of reconstruction of mapped BRDFs normalized by mean mapped BRDF value, using (blue) our 5 best points of sampling, (red) 5 common industry directions.



Figure 2: RMS error of reconstruction of mapped BRDFs normalized by mean mapped BRDF value, using (blue) our 5 best points of sampling, (red) 5 common industry directions.

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Figure 3: RMS error of reconstruction of mapped BRDFs normalized by mean mapped BRDF value, using (blue) our 5 best points of sampling, (red) 5 common industry directions.



Figure 4: RMS error of reconstruction of mapped BRDFs normalized by mean mapped BRDF value, using (blue) our 5 best points of sampling, (red) 5 common industry directions.



Figure 5: RMS error of reconstruction of mapped BRDFs normalized by mean mapped BRDF value, using (blue) our 5 best points of sampling, (red) 5 common industry directions.

2 Quality Matrices

2.1 MERL

Reconstructions of all 100 MERL materials using an increasing number of samples, *n*. Note in the reference images that for some materials (e.g. alumina-oxide, beige-fabric, nylon, pink-fabric) measurement artifacts are present. Generally our method handles these well.



Figure 6: Reconstructions of MERL BRDF samples. The BRDFs are rendered as spheres, illuminated by a front-light at a direction of [1, 1, 1], and a back-light causing grazing angle reflections at [-1, -1, -3]. Reconstructions are made with $n = \{1, 2, 3, 5, 10, 20\}$ sampling points. References are shown in the right column



Figure 7: Reconstructions of MERL BRDF samples. The BRDFs are rendered as spheres, illuminated by a front-light at a direction of [1, 1, 1], and a back-light causing grazing angle reflections at [-1, -1, -3]. Reconstructions are made with $n = \{1, 2, 3, 5, 10, 20\}$ sampling points. References are shown in the right column



Figure 8: Reconstructions of MERL BRDF samples. The BRDFs are rendered as spheres, illuminated by a front-light at a direction of [1, 1, 1], and a back-light causing grazing angle reflections at [-1, -1, -3]. Reconstructions are made with $n = \{1, 2, 3, 5, 10, 20\}$ sampling points. References are shown in the right column



Figure 9: Reconstructions of MERL BRDF samples. The BRDFs are rendered as spheres, illuminated by a front-light at a direction of [1, 1, 1], and a back-light causing grazing angle reflections at [-1, -1, -3]. Reconstructions are made with $n = \{1, 2, 3, 5, 10, 20\}$ sampling points. References are shown in the right column



Figure 10: Reconstructions of MERL BRDF samples. The BRDFs are rendered as spheres, illuminated by a front-light at a direction of [1, 1, 1], and a back-light causing grazing angle reflections at [-1, -1, -3]. Reconstructions are made with $n = \{1, 2, 3, 5, 10, 20\}$ sampling points. References are shown in the right column



Figure 11: Reconstructions of MERL BRDF samples. The BRDFs are rendered as spheres, illuminated by a front-light at a direction of [1, 1, 1], and a back-light causing grazing angle reflections at [-1, -1, -3]. Reconstructions are made with $n = \{1, 2, 3, 5, 10, 20\}$ sampling points. References are shown in the right column



Figure 12: Reconstructions of MERL BRDF samples. The BRDFs are rendered as spheres, illuminated by a front-light at a direction of [1, 1, 1], and a back-light causing grazing angle reflections at [-1, -1, -3]. Reconstructions are made with $n = \{1, 2, 3, 5, 10, 20\}$ sampling points. References are shown in the right column



Figure 13: Reconstructions of MERL BRDF samples. The BRDFs are rendered as spheres, illuminated by a front-light at a direction of [1, 1, 1], and a back-light causing grazing angle reflections at [-1, -1, -3]. Reconstructions are made with $n = \{1, 2, 3, 5, 10, 20\}$ sampling points. References are shown in the right column



Figure 14: Reconstructions of MERL BRDF samples. The BRDFs are rendered as spheres, illuminated by a front-light at a direction of [1, 1, 1], and a back-light causing grazing angle reflections at [-1, -1, -3]. Reconstructions are made with $n = \{1, 2, 3, 5, 10, 20\}$ sampling points. References are shown in the right column



Figure 15: Reconstructions of MERL BRDF samples. The BRDFs are rendered as spheres, illuminated by a front-light at a direction of [1, 1, 1], and a back-light causing grazing angle reflections at [-1, -1, -3]. Reconstructions are made with $n = \{1, 2, 3, 5, 10, 20\}$ sampling points. References are shown in the right column

2.2 Cornell

Reconstructions of Cornell Reflectance Database samples for an increasing number of samples. First figure presents point-sampling. The second figure presents spherical sampling.



Figure 16: Reconstructions of unknown samples (10 Cornell Reflectance Database samples not used at all for computing principal components (PCs) and sample directions). The BRDFs are rendered as spheres, illuminated by a front-light at a direction of [1,1,1], and a back-light causing grazing angle reflections at [-1,-1,-3]. Reconstructions are made with $n = \{1,2,3,5,10,20\}$ sampling points. Finally, the far right column shows reference renderings of the true BRDFs. We see that generally 3-10 measurements are sufficient to capture the true appearance of a material. Note that "Cayman" and "Mystique" are complex car-paints and are not fully explained by the number of samples used here.



Figure 17: Reconstructions of Cornell samples not shown in main paper, simulating BRDF capture using a sphere. Note that the complex "Mystique" color-changing properties are correctly captured by 5 images.